

Lecture : Formal definitions

Def 1 (Block code): An (n, M) block code is a subset $\mathcal{L} \subseteq \mathcal{X}^n$ with $|\mathcal{L}| = M$.
 \downarrow
Blocklength

We hence have rate $R = \frac{\log M}{n}$.

Egs: (i) Rate of repetition code $\mathcal{L} = \{000, 111\}$ is $1/3$ and \mathcal{L} is a $(3, 2)$ block code.

(ii) Rate of single parity-check code $\mathcal{L} \subseteq \{0, 1\}^n$ is ?
and it is a $(_, _)$ block code.

(Recall): From basic communication theory, for a given noisy channel $W = (P(y|c) : c \in \mathcal{L}, y \in \mathcal{Y})$, the decoder that minimizes the error probability is the "maximum a-posteriori probability" (MAP) decoder:

$$\hat{c} = \underset{c \in \mathcal{L}}{\operatorname{argmax}} P(c|y).$$

HW1: Provide/read up a proof of this fact.

Now, suppose that $c \sim \operatorname{Unif}(\mathcal{L})$. Then,

$$\hat{\underline{c}} = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} \frac{P(y|\underline{c})P(\underline{c})}{P(y)}$$

$$= \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} \underbrace{\frac{1}{M P(y)}}_{\text{constant!}} \cdot P(y|\underline{c}) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} P(y|\underline{c})$$

\triangleq ML decoder
("maximum likelihood").

What is ML decoding for the BSC?

For a fixed $\underline{c} \in \mathcal{L}$ and any $y \in \{0,1\}^n$,

$$\begin{aligned} P(y|\underline{c}) &= p^{d(\underline{c}, y)} (1-p)^{n-d(\underline{c}, y)} \end{aligned}$$

where $d(\underline{c}, y) = d(y, \underline{c}) \triangleq d$ is the "Hamming distance" b/w \underline{c} and y ,

i.e., the # positions where \underline{c} & y differ.

Hence, $ML(y) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} P(y|\underline{c}) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmin}} d(\underline{c}, y)$, when $p < 1/2$.

Lemma 1: $d(\cdot, \cdot)$ is a metric over \mathcal{X}^n .

Pf: HW.

Def 2 (Minimum distance): The minimum distance of a block code \mathcal{L}

$$d(\mathcal{L}) = d_{\min}(\mathcal{L}) = \min_{\substack{c_1, c_2 \in \mathcal{L}, \\ c_1 \neq c_2}} d(c_1, c_2).$$

An (n, M) block code with min. dist. d is written as an (n, M, d) block code.

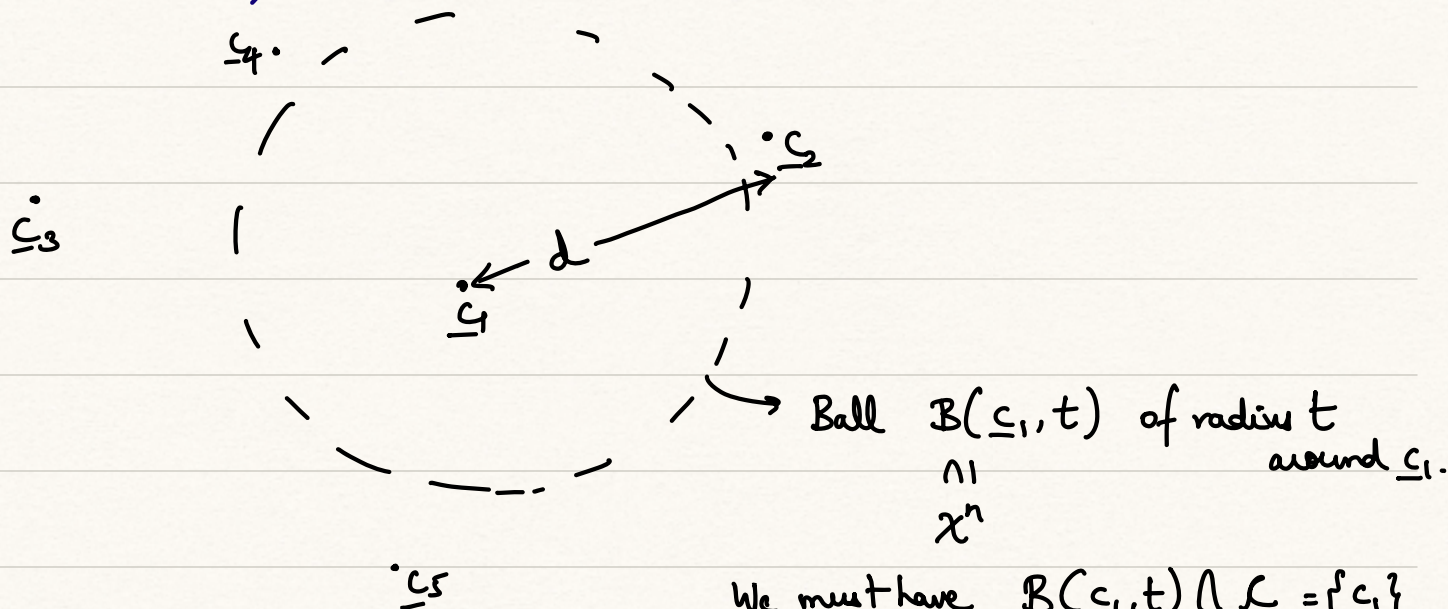
Error detection/correction tied to distance

Thm 1: For an (n, M, d) block code \mathcal{L} , \exists a decoder that detects up to $d-1$ bit-flip errors.

This decoder obeys

$$\mathcal{D}(y) = \begin{cases} y, & \text{if } y \in \mathcal{L}, \\ \text{ERROR, o.w.} \end{cases}$$

Pf: (Picture)



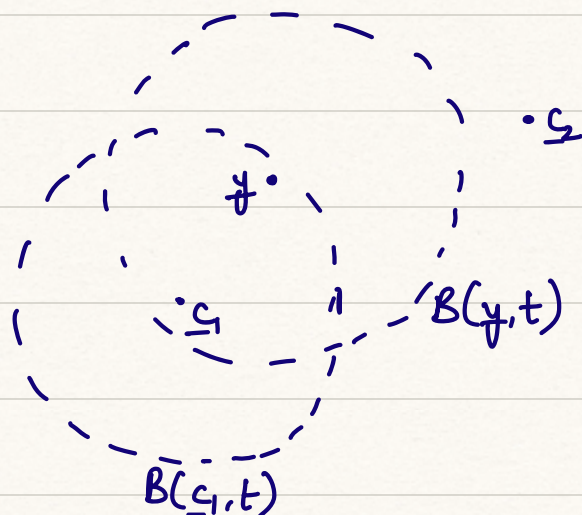
We must have $B(c_1, t) \cap \mathcal{L} = \{c_1\}$,
if $t \leq d-1$; else, contradiction \square

Thm 2: For an (n, M, d) block code \mathcal{L} , \exists a decoder that corrects $t \leq \lfloor \frac{d-1}{2} \rfloor$ bit-flip errors.

This decoder is the **minimum distance decoder**

$$\hat{\mathcal{C}}(y) = \underline{c}, \text{ if } B(y, t) \cap \mathcal{L} = \{\underline{c}\}.$$

Pf: (Picture)



We cannot have $\underline{c}_2 \neq \underline{c}_1$ s.t. $\underline{c}_2 \in B(y, t)$, as then

$$\begin{aligned} d(\underline{c}_1, \underline{c}_2) &\leq d(\underline{c}_1, y) + d(\underline{c}_2, y) \\ &\leq 2t \leq 2 \cdot \lfloor \frac{d-1}{2} \rfloor < d, \end{aligned}$$

a contradiction. \square

An aside: Erasures are channel noise that behave as follows:

$$\underline{c} = (c_1, c_2, \dots, c_{n-1}, c_n) \xrightarrow[\text{channel}]{\text{Erase}} y = (c_1, ?, c_3, \dots, c_{n-1}, ?)$$

Selected codeword symbols are replaced with a '?'.

Thm: For an (n, M, d) block code \mathcal{L} , there is a decoder that corrects up to $d-1$ erasures.

Pf: HW. (state a decoder and prove its erasure-correction property).

Addendum: Proof that the MAP decoder is optimal for minimizing error prob.
(23-1-26)

Given a channel W and an Encoder (Enc) (or equivalently, the code \mathcal{L}), we wish to identify a Decoder (Dec) that minimizes

$$P_{\text{err}}(\mathcal{L}) \triangleq P_u[\hat{m} \neq m] \\ = P_u[Dec(y) \neq c] \quad \left[\text{Assuming that } Enc \text{ is a one-one map from } \mathcal{M} \text{ to } \mathcal{L} \right]$$

$$= \sum_{c, y: D(y) \neq c} P(y, c) \quad [D \equiv Dec]$$

$$= \sum_y P(y) \sum_{c: D(y) \neq c} P(c|y),$$

over D .

Clearly,

$\arg \min_D P_{\text{err}}(\mathcal{L})$ computes, for each y ,

[Think about this!]

$$\arg \min_{D(y)} \sum_{\mathcal{L}: D(y) \neq \mathcal{L}} P(\mathcal{L} | y) .$$

We thus obtain that for any fixed $y \in \mathcal{Y}^n$, we must have

$$D(y) = \max_{\mathcal{L} \in \mathcal{L}} P(\mathcal{L} | y) .$$

(MAP estimator)